FINAL EVENT 2023

December 18, 2023 NTUA, Athens Zografou Campus











A methodological framework for low-cost cooperative DGNSS/INS-based robust positioning in safety critical connected vehicle applications

09.00 - 09.30	REGISTRATION
09.30 - 09.50	Welcome Address Vassilis Gikas, RobPos4VApp Coordinator, School of Rural, Surveying and Geoinformatics Engineering, NTUA, Greece Ioannis Chatjigeorgiou, Rector of National Technical University of Athens, NTUA, Greece Charalampos Ioannidis, Dean of School of Rural, Surveying and Geoinformatics Engineering, NTUA, Greece
09.50 - 10.10	Spatiotemporal data analysis for sustainability science Laura Ruotsalainen, University of Helsinki, Finland
10.10 - 10.30	Multi-agent DGNSS collaborative navigation: Fundamentals, limitations, and new frontiers Alex Minetto, Polytechnic of Turin, Italy
10.30 - 10.45	CAV applications requiring accurate positioning data: Considerations for RobPos4VApp project Ioannis Papamichail, Technical University of Crete, Greece
10.45 – 11.00	Introduction to RobPos4VApp: objectives, approach and challenges Vassilis Gikas, School of Rural, Surveying and Geoinformatics Engineering, NTUA, Greece
11.00 - 11.30	COFFEE BREAK
11.30 - 11.50	RobPos4VApp: Development and testing of MADM algorithms for optimal vehicle selection Athanasios Panagopoulos / Theodore Kapsis, School of Electrical and Computer Engineering, NTUA, Greece
11.50 – 12.10	RobPos4VApp: The C-DGNSS/INS position algorithm and performance evaluation Thanassis Mpimis, School of Rural, Surveying and Geoinformatics Engineering, NTUA, Greece
12.10 – 12.30	Dynamic road traffic management for connected and automated vehicles Evangelos Mitsakis, Centre for Research and Technology Hellas, Hellenic Institute of Transport, Greece
12.30 – 12.50	Artificial Intelligence for Connected Vehicles Traffic Safety George Yannis, School of Civil Engineering, NTUA, Greece
12.50 - 13.00	Closing Remarks
13.00 – 14.00	LUNCH BUFFET

__ http://robpos4vapp.survey.ntua.gr/

